

Signals and its properties

Signals and codes (SK)

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Faculty of Transportation Sciences, CTU in Prague

Lecture 1



Lecture goal and content

Goal

- Understand what is signal, know basic types of signal and their basic characteristic values and reveal that signals are everywhere around us.

Content

- Signals
 - what is it?
 - types of signals
 - examples of signals
 - characteristic values of signals
 - instantaneous value
 - average value
 - signal energy
 - signal power
 - effective value

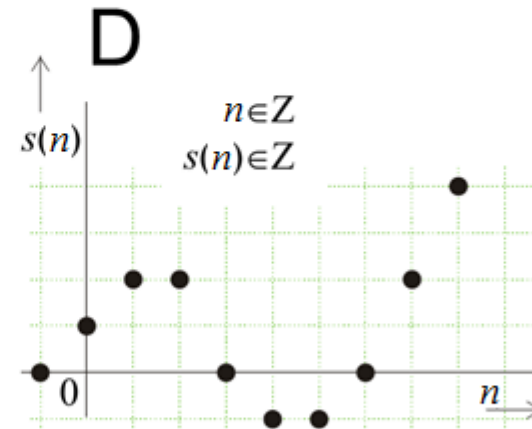
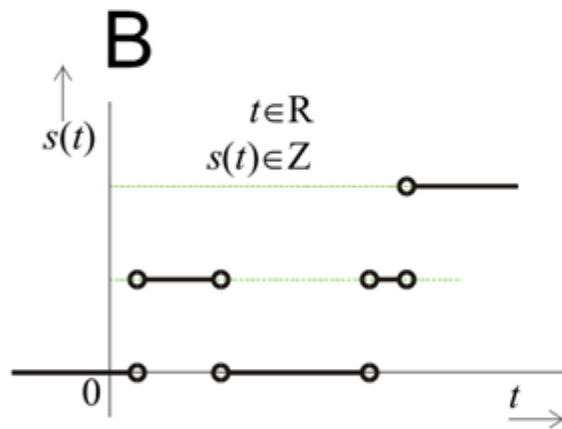
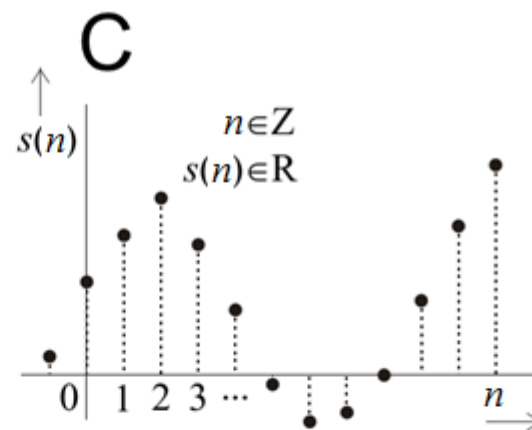
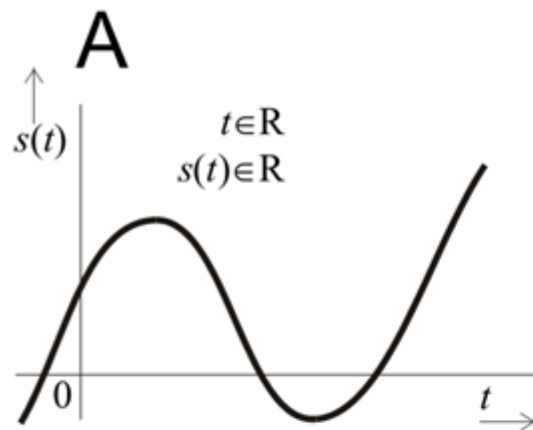
What is signal?

Definition: an abstraction of any measurable quantity that is a function of one or more independent variables such as time or space. For this course it is some function of time.

Examples:

- A voltage or a current in a circuit
- Electrocardiograms
- Sinusoid $A \cdot \sin(\omega t + \varphi)$
- Speech/music
- Intensity of light radiation
- Acoustic pressure
- Image, video
- etc.

Signal types: continuous (C), discrete (D)



Signals continuous in value, Signals continuous in value

Signals discrete in value, Signals discrete in value

Quantized signals

Signals in continuous time

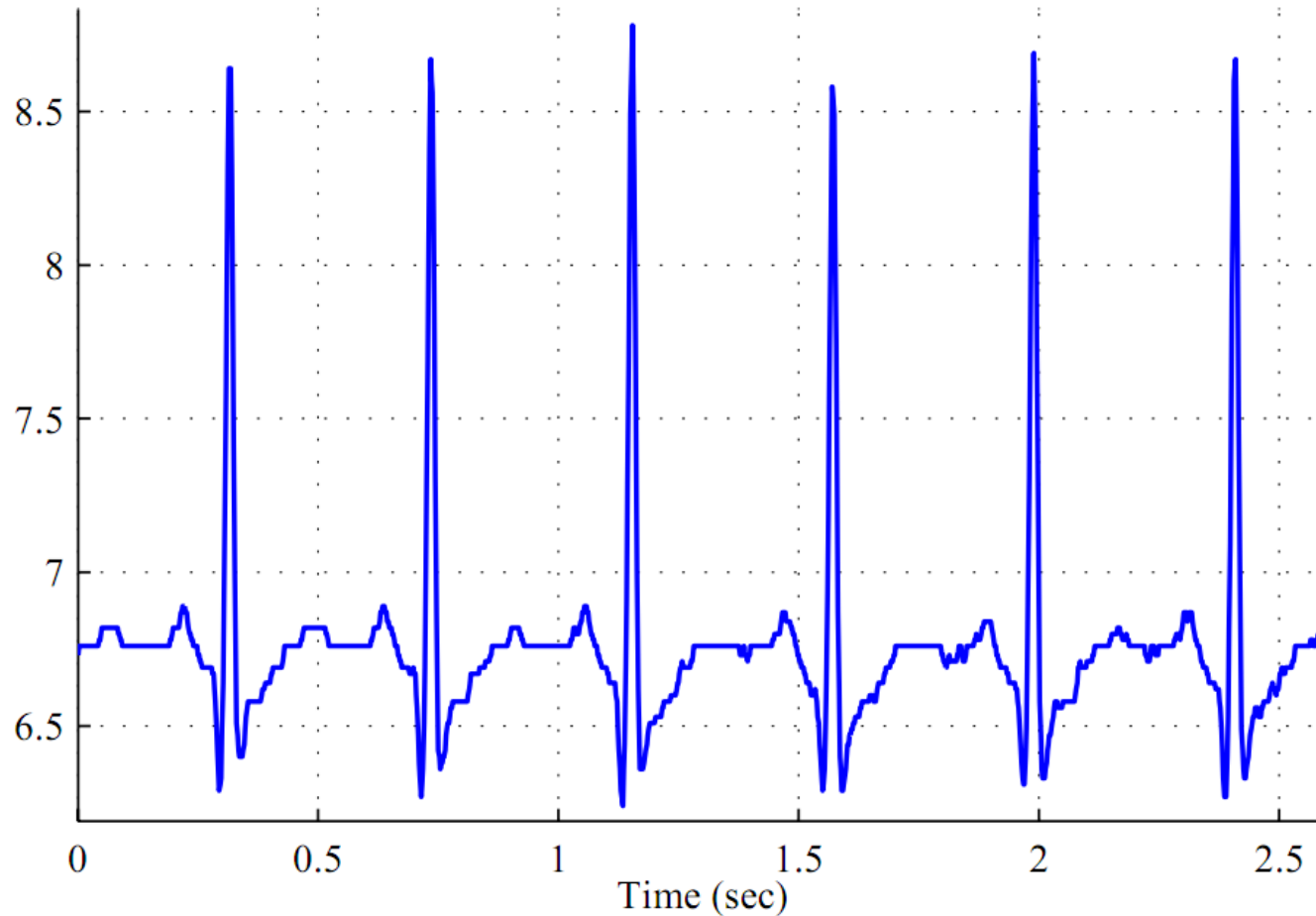
Signals in discrete time,
Sampled signals, sequences

Basic signal operations

- Time shift: $s(t-t_0)$ and $s[n-n_0]$
 - If $t_0 > 0$ or $n_0 > 0$, signal is shifted to the right
 - If $t_0 < 0$ or $n_0 < 0$, signal is shifted to the left
- Time reversal: $s(-t)$ and $s[-n]$
- Time scaling: $s(at)$ and $s[an]$
 - If $a > 1$, signal is compressed
 - If $1 > a > 0$, signal is stretched
- Signal scaling: $as(t)$ and $as[n]$
 - If $a > 1$, signal has higher values
 - If $1 > a > 0$, signal has lower values

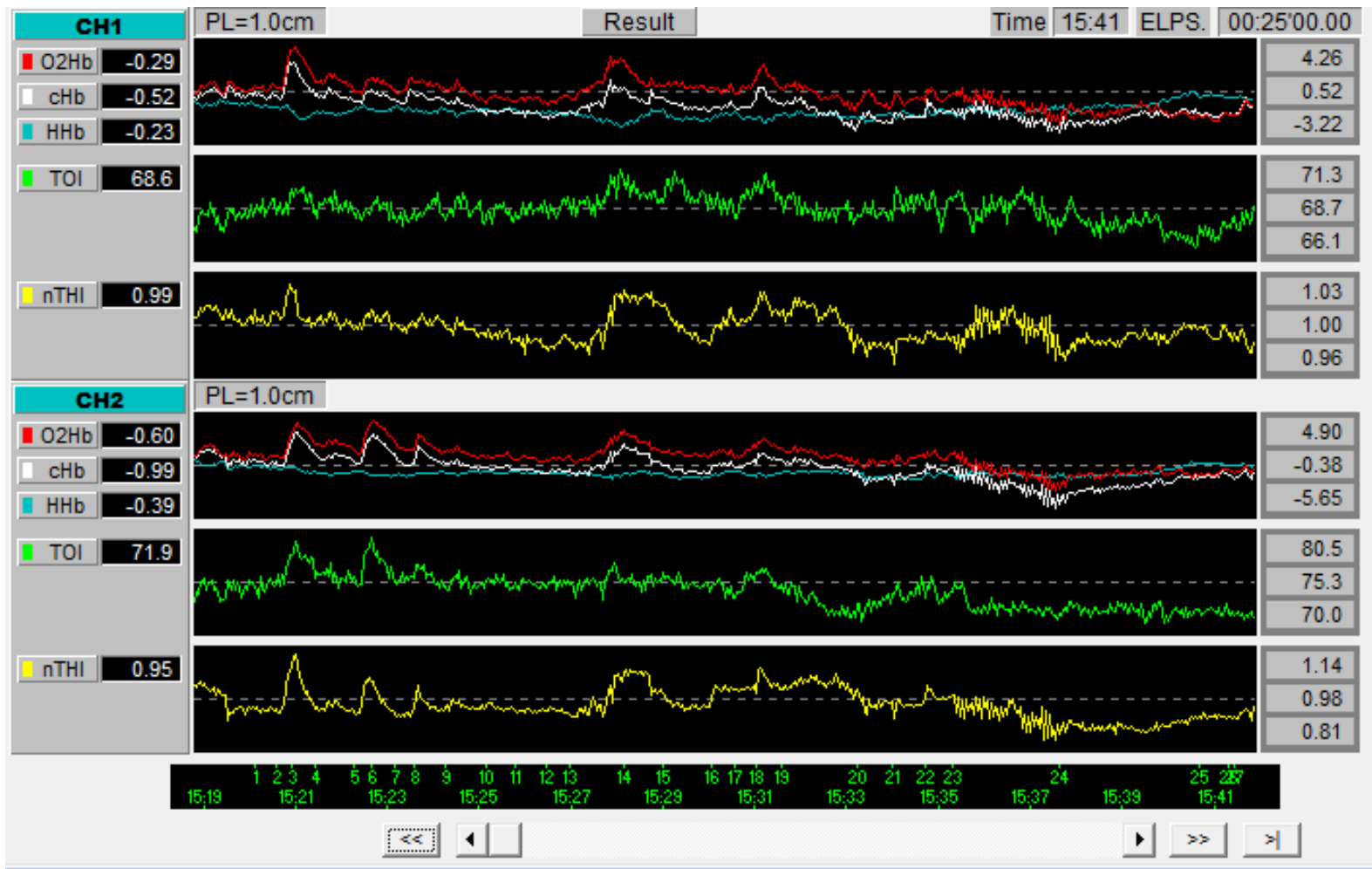
Signal examples

- ECG (electrocardiogram), in Czech EKG



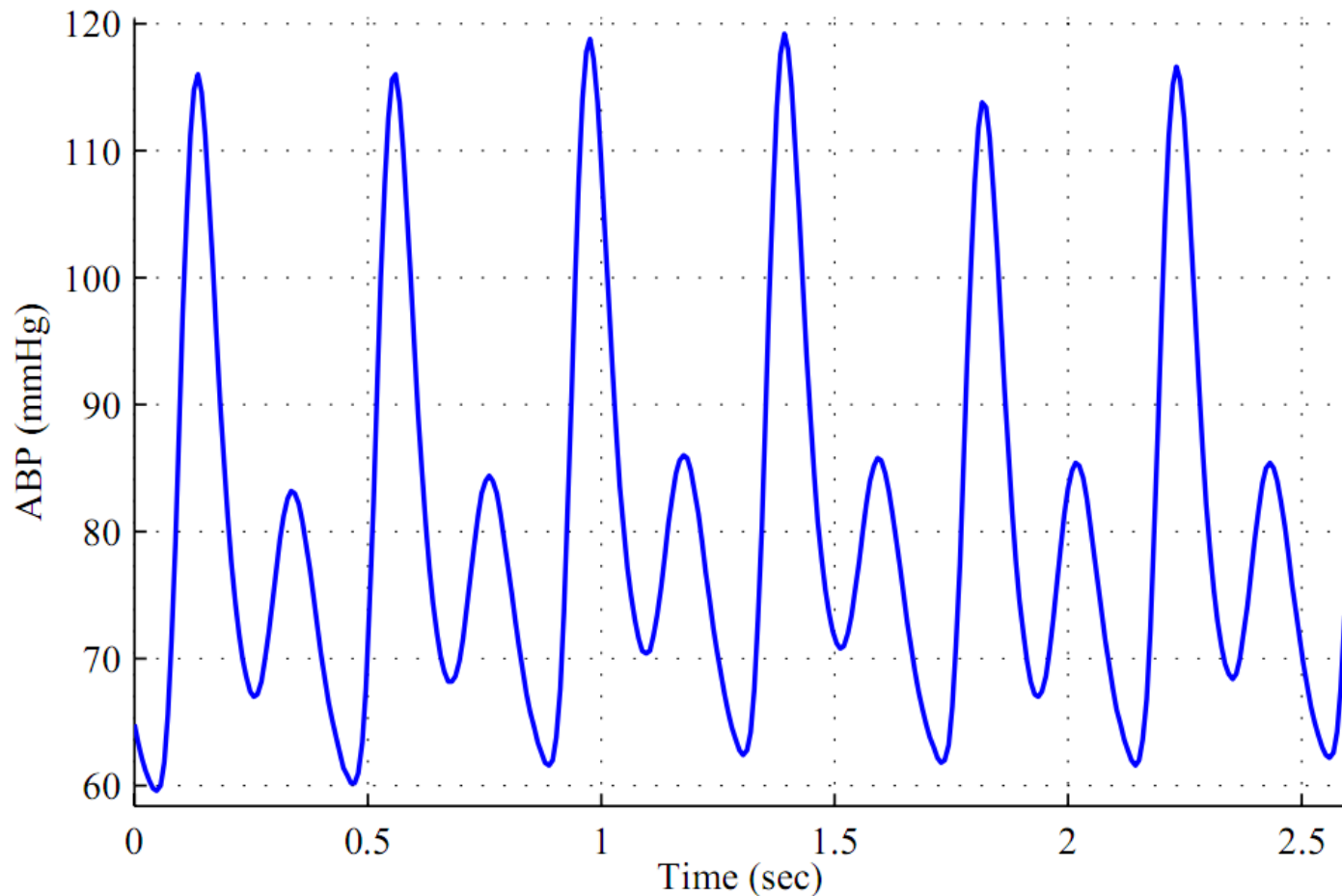
Signal examples

- EEG (electroencephalogram)



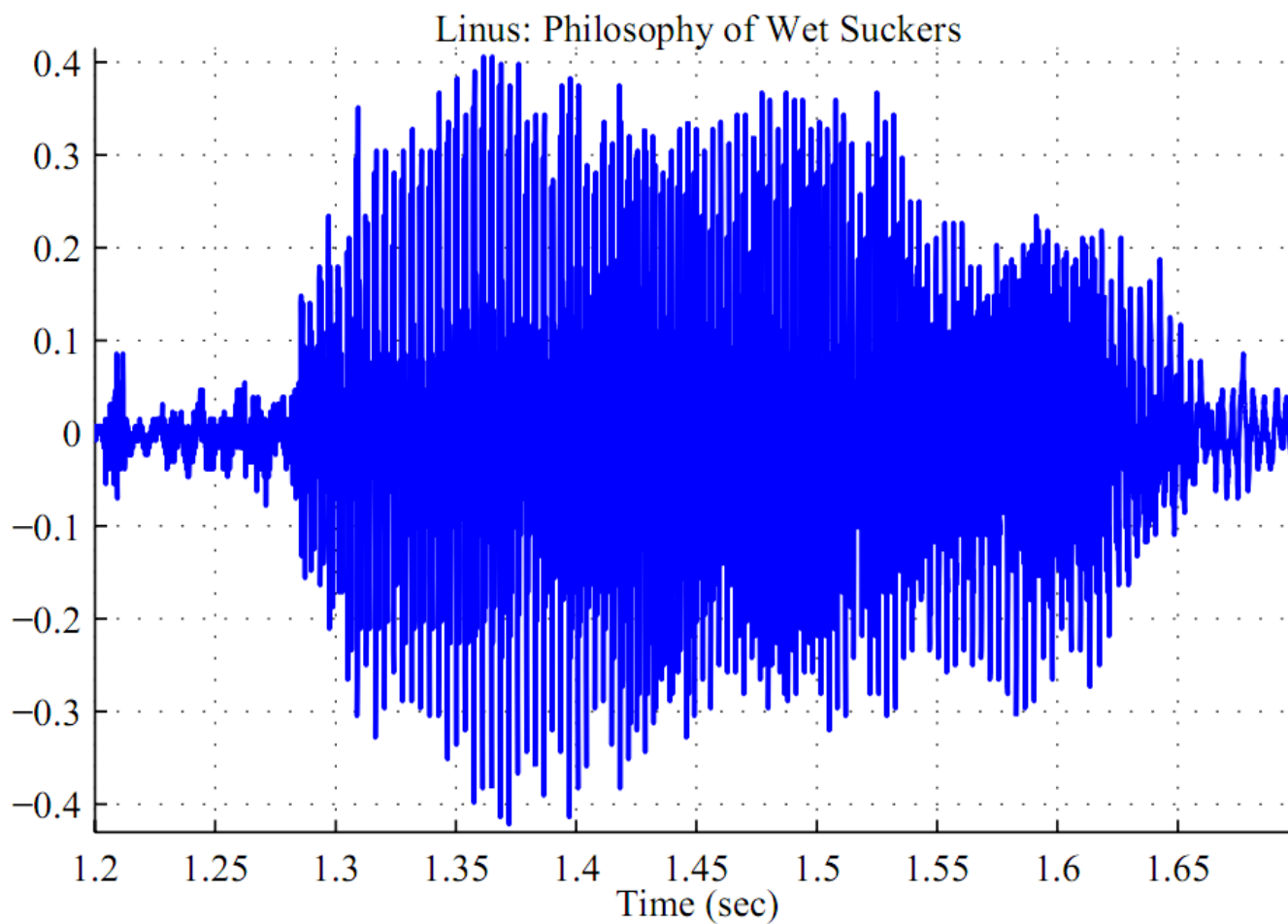
Signal examples

- Arterial pressure (tepenný tlak)



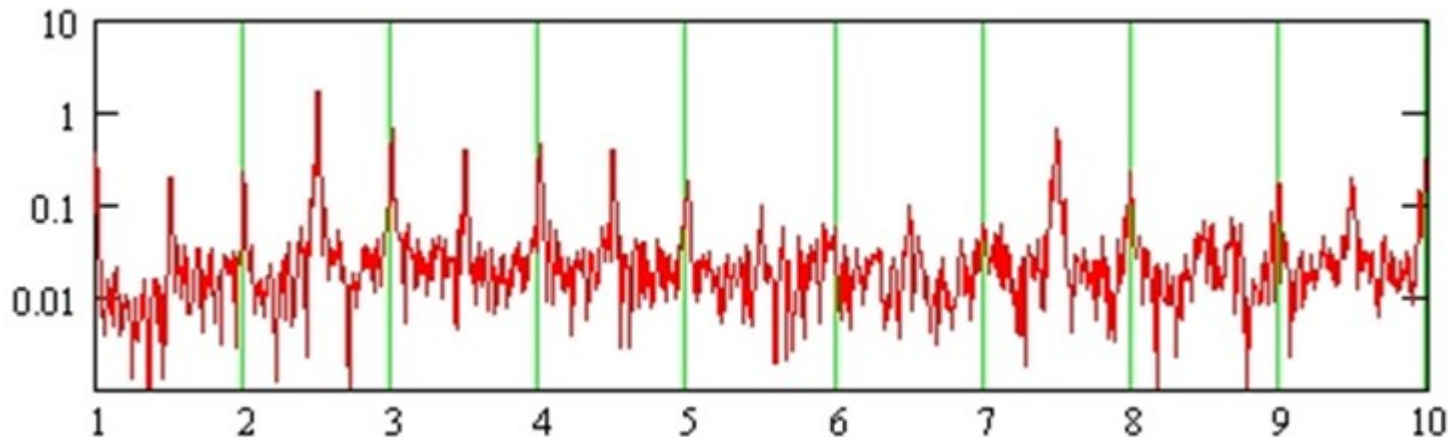
Signal examples

- Speech (řeč)



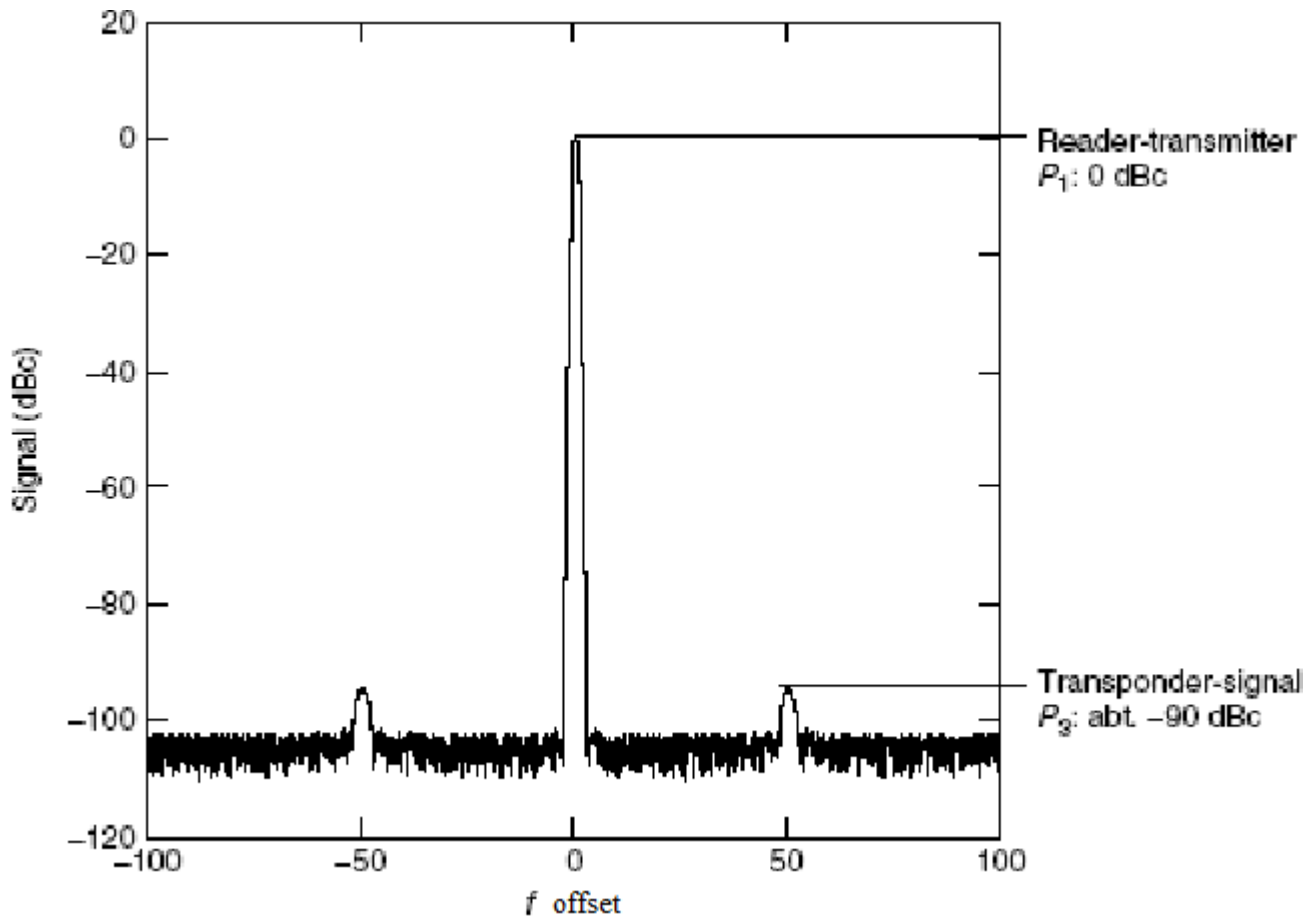
Signal examples

- NVH (Noise, vibration, and harshness) (hluk a vibrace)
 - Here is the noise **spectrum** of Michael Schumacher's Ferrari at 16680 rpm, showing the various harmonics. The x axis is given in terms of multiples of engine speed. The y axis is logarithmic, and uncalibrated (https://en.wikipedia.org/wiki/Noise,_vibration,_and_harshness).



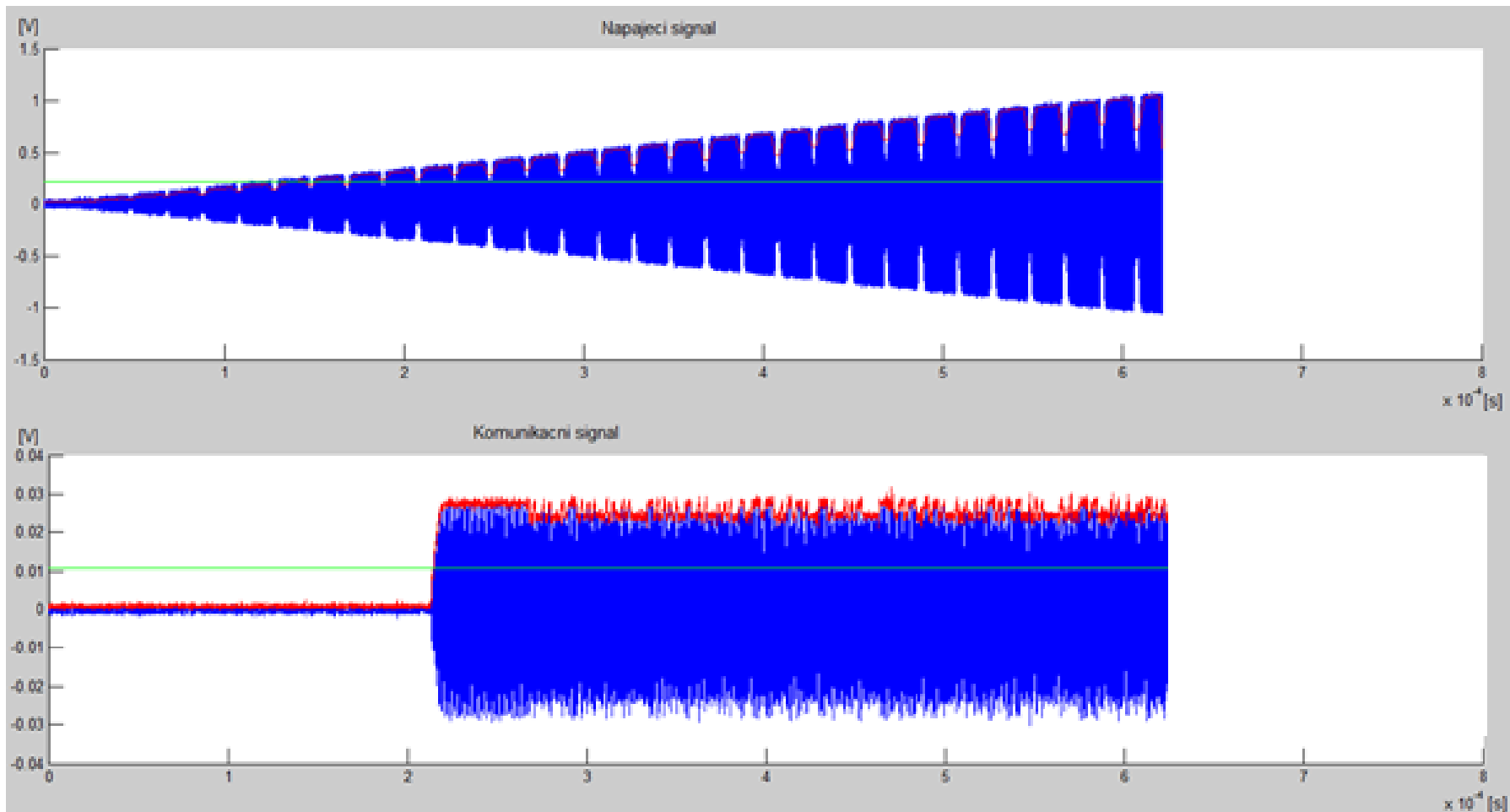
Signal examples

- RFID (not only in transport)



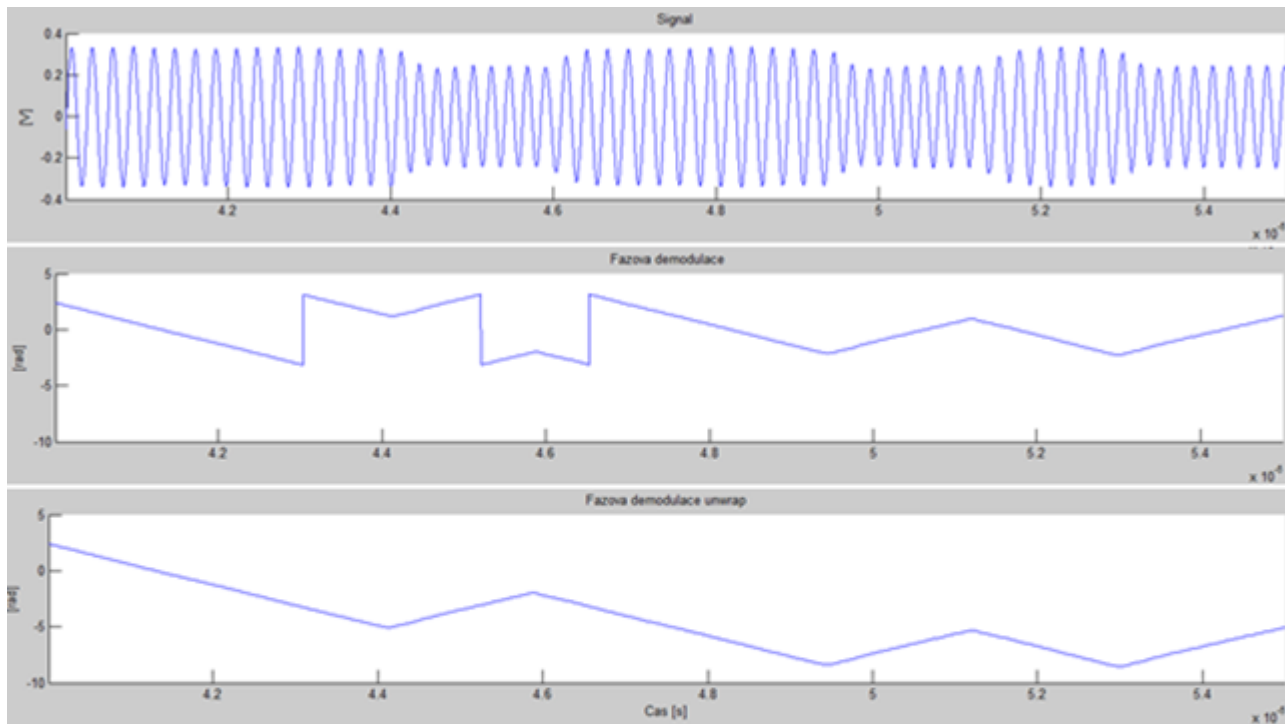
Signal examples

- Eurobalise – AM modulated tele-powering signal and up-link signal (balise response) (napájecí a komunikační signál (odpověď balízy))

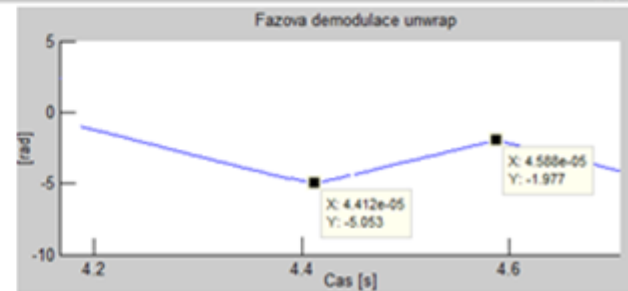


Signal examples

- Eurobalise – phase demodulation of FSK modulated up-link signal

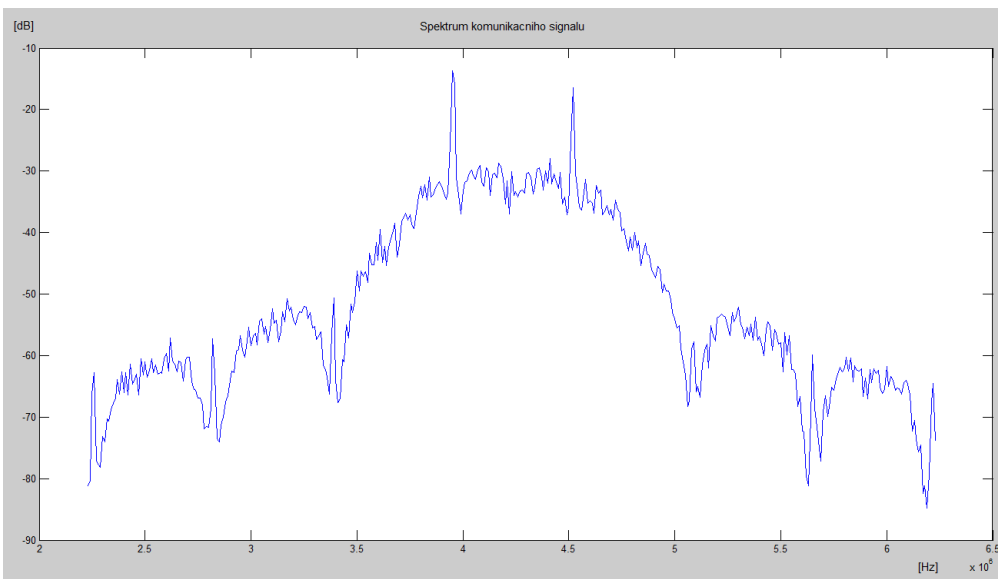


$$f = \frac{\omega_1 - \omega_2}{2 \cdot \pi \cdot (t_1 - t_2)} + f_{\text{centre}}$$

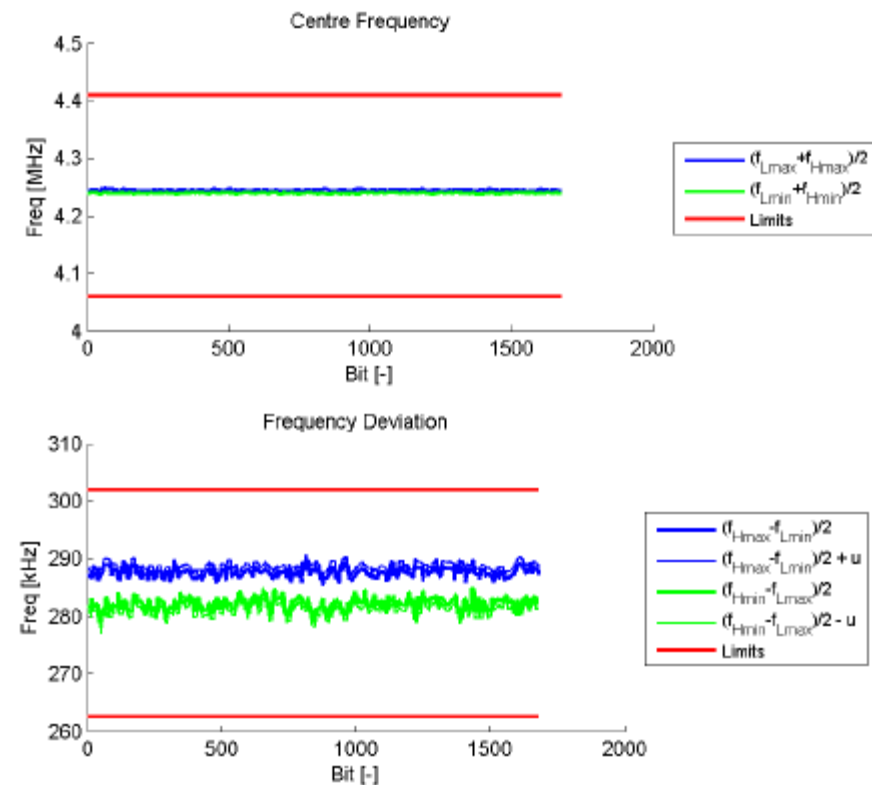


Signal examples

- Eurobalise – spectrum of up-link signal

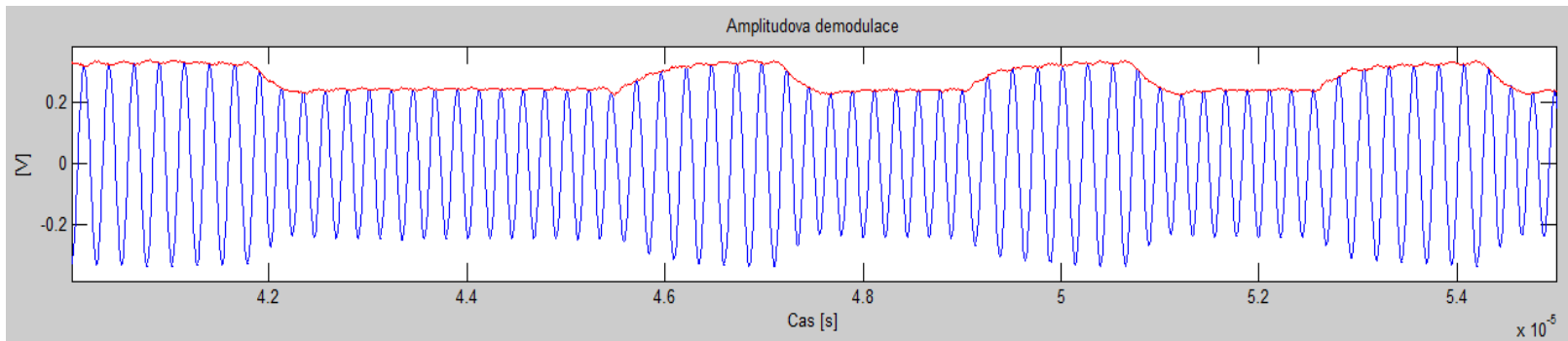


- Eurobalise – up-link signal: centre frequency and deviation

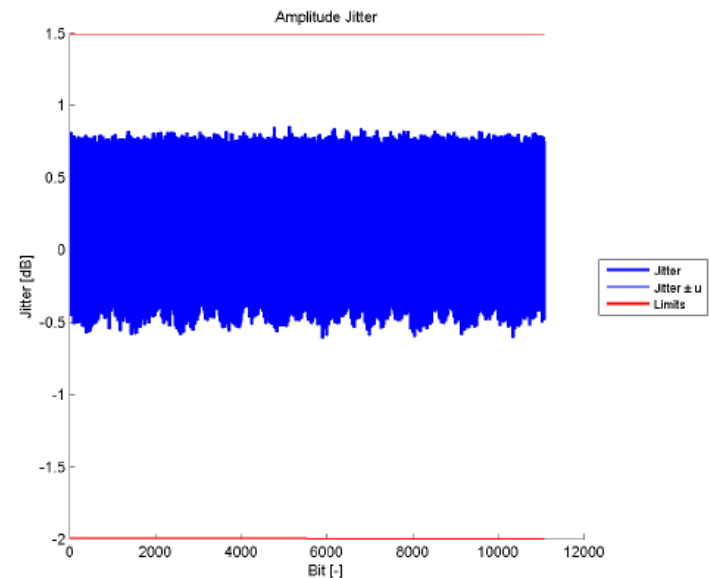


Signal examples

- Eurobalise – amplitude demodulation of up-link signal

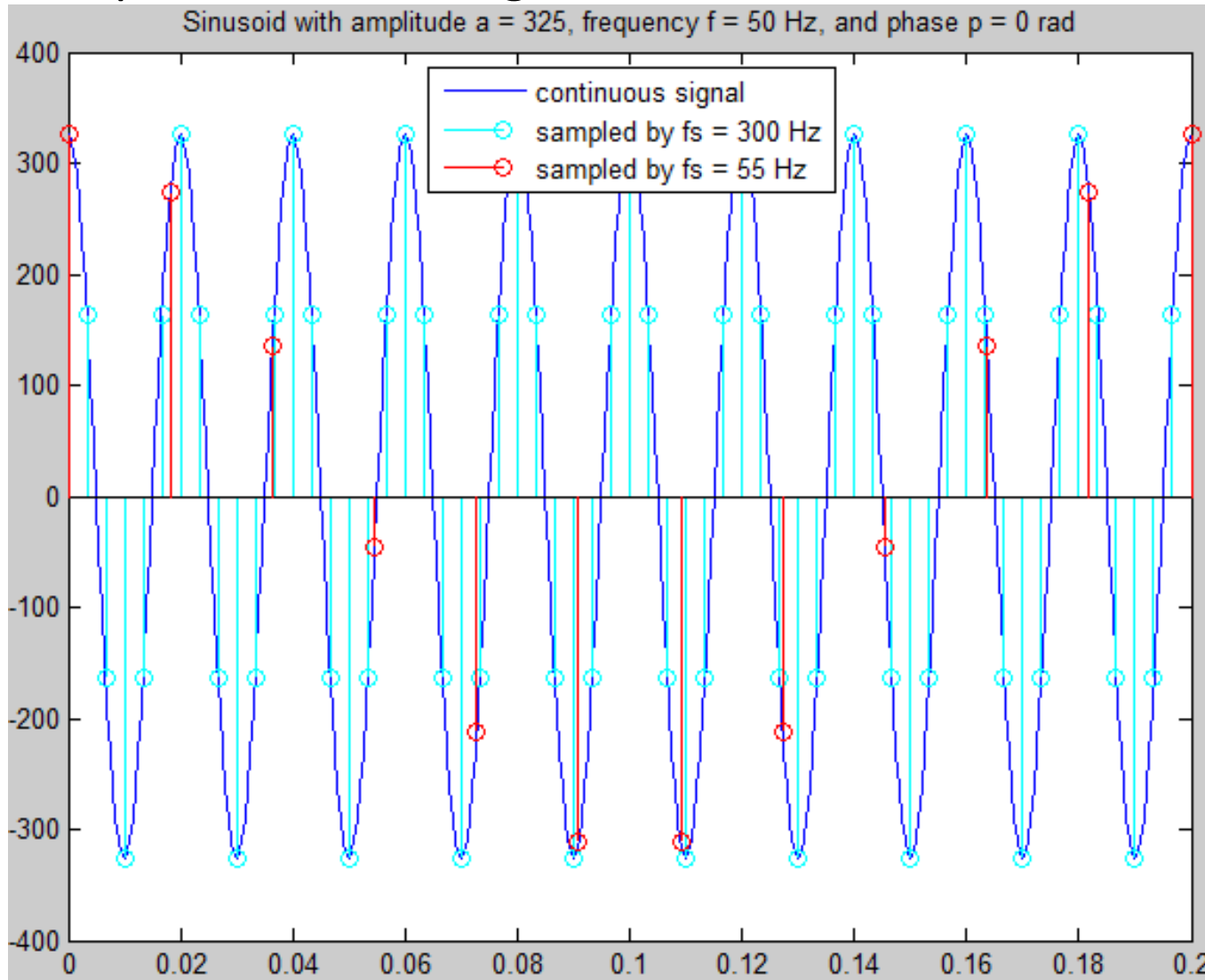


- Eurobalise – amplitude jitter
(kolísání amplitudy)



Signal examples

- Sampled socket voltage 230 V



Signal examples

- Video detection of vehicles



pictures from https://www.youtube.com/watch?v=F_M_skebbpA

Characteristic values of signals $x(t)$

① Instantaneous value $x(t_i)$, $x[m_i]$

Exp. 1.1: Given signal $x(t) = 325 \cdot \sin(2\pi \cdot 50 \cdot t)$

Find instantaneous value of the signal for time instant $t = 10 \text{ ms}$.

Sol.: $x(10 \cdot 10^{-3}) = 325 \cdot \sin(2\pi \cdot 50 \cdot 0.01) = 325 \cdot \sin\pi = \underline{0}$

Note: x is dimensionless

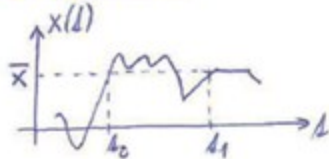
Q: Is socket voltage 230 V safe at time instant $t = 10 \text{ ms}$?

A: Yes, BUT dangerous touch before $t > 0 \text{ s}$, see RMS value below.

② Average value \bar{x} in a time interval

- Continuous time (CT):

$$\bar{x} = \frac{1}{t_1 - t_0} \int_{t_0}^{t_1} x(t) dt$$

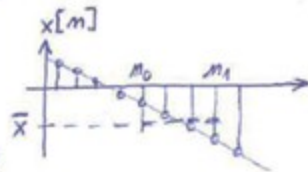


- periodic function: choose $t_1 - t_0 = T_0 \dots$ fundamental period

arbitrary time instant thus $\bar{x} = \frac{1}{T_0} \int_{t_i}^{t_i + T_0} x(t) dt$

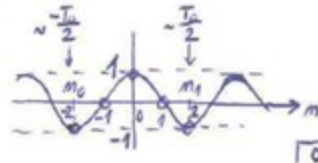
- Discrete time (DT)

$$\bar{x} = \frac{1}{m_1 - m_0 + 1} \sum_{n=m_0}^{m_1} x[n]$$



- periodic function: choose $m_1 = m_0 + \frac{T_0}{T_s} - 1$
sample period T_s

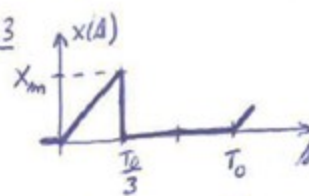
thus: $\bar{x} = \frac{T_s}{T_0} \sum_{n=m_0}^{m_0 + \frac{T_0}{T_s} - 1} x[n]$



Exp. 1.2: $x(t) = e^{-0.2t}$ Find average value \bar{x} in time interval $t \in (0; 2) \text{ s}$.
(Note: Transient phenomena equation $\dots e^{-\frac{t}{\tau}}$, thus $\tau = 5 \text{ s}$)

Sol.: $\bar{x} = \frac{1}{2-0} \int_0^2 e^{-0.2t} dt = \frac{1}{2} \left[\frac{-1}{0.2} e^{-0.2t} \right]_0^2 = \frac{-5}{2} (e^{-0.4} - 1) = \underline{0.8242}$

Exe. 1.3



Find average value of the signal $x(t)$
(note: time interval = one fundamental period T_0)
(note: result is apparent at first glance)

Sol.: $\bar{x} = \frac{1}{T_0} \int_0^{T_0} x(t) dt = \frac{1}{T_0} \int_0^{T_0/3} \frac{X_m}{T_0/3} t dt = \frac{3X_m}{T_0^2} \left[\frac{t^2}{2} \right]_0^{T_0/3} = \frac{3X_m}{T_0^2} \cdot \frac{T_0^2}{3^2 \cdot 2} = \underline{\frac{X_m}{6}}$

Exe. 1.4: $x[m] = 325 \cdot \sin(2\pi \cdot 50 \cdot \frac{1}{200} \cdot m)$ $\frac{1}{200} = T_s$

Find average value of given discrete time periodic signal.

Sol.: $T_0 = \frac{1}{f_0} = \frac{1}{50} \text{ s}$, $T_s = \frac{1}{200} \text{ s} \Rightarrow \frac{T_0}{T_s} = 4$, $m_0 = 0$, $m_1 = 3$

$\bar{x} = \frac{1}{3-0+1} \sum_{n=0}^3 325 \cdot \sin(\frac{\pi}{2} \cdot n) = \underline{0}$

③ Signal energy E

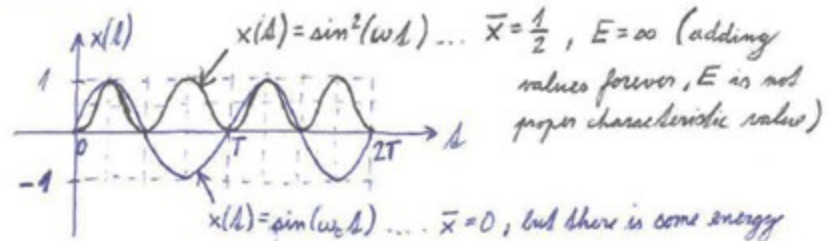
← energy signals have $0 < E < \infty$

CT: $E = \int_{-\infty}^{\infty} |x(t)|^2 dt$

note: absolute value in the formulas is important for complex signals (otherwise is not necessary)

DT: $E = \sum_{n=-\infty}^{\infty} |x[n]|^2$

Demo:



4) Signal power P ← power signals have $0 < P < \infty$
 - (average) value of signal energy over a time interval (usually period).
 (note: physics analogy: $p = \frac{dW}{dt}$)

General CT signals:

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

General DT signals:

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2$$

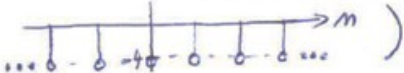
Periodic CT signals:

$$P = \frac{1}{T_0} \int_{t_i}^{t_i+T_0} |x(t)|^2 dt$$

Periodic DT signals:

$$P = \frac{1}{N} \sum_{m=n_i}^{n_i+N} |x[m]|^2, \text{ where}$$

$$N = \frac{T_0}{T_s} \dots \text{ samples per period}$$

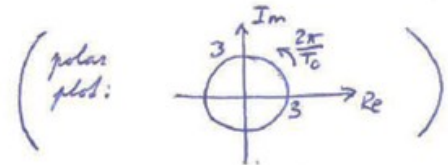
b) $x[m] = -4 \forall m$ (stem plot: )

$$\text{Sol.: } E = \sum_{m=-\infty}^{+\infty} |x[m]|^2 = \infty \cdot 16 = \infty$$

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2 = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N 16 = \lim_{N \rightarrow \infty} \frac{2N+1}{2N+1} \cdot 16 = 16$$

$$X_{RMS} = \sqrt{P} = 4$$

c) $x(t) = 3 \cdot e^{j \frac{2\pi}{T_0} t}$



$$\text{Sol.: } E = \int_{-\infty}^{\infty} |x(t)|^2 dt = 9 \cdot \infty = \infty$$

$$P = \frac{1}{T_0} \int_0^{T_0} |x(t)|^2 dt = \frac{1}{T_0} \int_0^{T_0} |3 \cdot e^{j \frac{2\pi}{T_0} t}|^2 dt = \frac{1}{T_0} \cdot 9 \cdot [t]_0^{T_0} = 9$$

$$X_{RMS} = \sqrt{P} = 3$$

Energy vs. power - questions and answers

Q: Is some energy signal also power signal?

A: No. If $0 < E < \infty$, then $P = 0$. If $0 < P < \infty$, then $E = \infty$.

Q: Are all signals either energy or power signals?

A: No. Any infinite duration increasing amplitude signal will not be either.
 (example: $x(t) = t^2$ is neither power signal ($P = \infty$) nor energy signal ($E = \infty$)).

Vocabulary: instantaneous value - okamžitá hodnota

time instant - časový okamžik

average value - průměrná hodnota

fundamental period - základní perioda

arbitrary - libovolný

transient phenomenon - přechodný jev

5) Effective value of a signal X_{RMS} (root mean square)

$$X_{RMS} = \sqrt{P}$$

- equivalent constant signal with the same power as $x(t)$

Exe. 1.5: Find energy, power and effective value of signals:

a) $x(t) = \begin{cases} 10 & \dots 0 \leq t \leq 1 \\ 0 & \dots \text{otherwise} \end{cases}$ (plot of $x(t)$)

$$\text{Sol.: } E = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_0^1 10^2 dt = 100 \cdot [t]_0^1 = 100$$

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt = \lim_{T \rightarrow \infty} \frac{1}{2T} \cdot 100 = 0$$

$$X_{RMS} = \sqrt{P} = 0$$

References

- Vejražka, František. Signály a soustavy / 4.vyd. Praha: ČVUT, 1996. 243 s. ISBN 80-01-00450-3., In Czech

